

Amendments to the Claims

This listing of claims will replace all prior versions, and listings, of claims in the application:

1. (Previously Presented) A method for performing motion estimation comprising:
receiving a stream of data comprising one or more bidirectionally interpolated frames (B-frame) and a plurality of anchor frames; and
unidirectionally predicting content of each B-frame from a temporally closest anchor frame, wherein, with respect to each B-frame:
if the temporally closest anchor frame is previous to the B-frame, only unidirectionally forward predicting the content of the B-frame from only the temporally closest anchor frame;
if the temporally closest anchor frame is subsequent to the B-frame, only unidirectionally backward predicting the content of the B-frame from only the temporally closest anchor frame; and
wherein the unidirectionally predicted B-frame that is predicted only from the temporally closest anchor frame comprises a frame that is defined as a bi-directionally predicted frame according to an encoding protocol for the stream of data.

2. (Original) The method of claim 1, wherein the content of the B-frames is unidirectionally predicted from the content of the temporally closest anchor frame and one or more motion vectors.
3. (Original) The method of claim 2, wherein the one or more motion vectors represent an activity measure of the temporally closest anchor frame.
4. (Original) The method of claim 3, wherein the motion vector is determined by a sum of absolute differences in activity within the temporally closest anchor frame.
5. (Canceled).
6. (Original) The method of claim 1, wherein the plurality of anchor frames and B-frames contain progressive video content.
7. (Original) The method of claim 1, wherein the plurality of anchor frames and B-frames contain interlaced video content.

Claims 7-19 (Canceled).

20. (Currently Amended) A computer ~~machine~~ readable ~~physical~~ storage-medium comprising having stored thereon a plurality of computer executable instructions that,

in response to being executed result, in an apparatus performing a method for motion estimation comprising:

receiving a stream of data comprising one or more bidirectionally interpolated frames (B-frame) and a plurality of anchor frames; and

unidirectionally predicting content of each B-frame from a temporally closest anchor frame, wherein, with respect to each B-frame:

if the temporally closest anchor frame is previous to the B-frame, only unidirectionally forward predicting the content of the B-frame from only the temporally closest anchor frame;

if the temporally closest anchor frame is subsequent to the B-frame, only unidirectionally backward predicting the content of the B-frame from only the temporally closest anchor frame; and

wherein the unidirectionally predicted B-frame that is predicted only from the temporally closest anchor frame comprises a frame that is defined as a bi-directionally predicted frame according to an encoding protocol for the stream of data.

21. (Currently Amended) The ~~computer machine readable physical storage~~ medium of claim 20, wherein the content of the B-frames is unidirectionally predicted from the content of the temporally closest anchor frame and one or more motion vectors.

22. (Currently Amended) The ~~computer machine readable physical storage~~ medium of claim 21, wherein the one or more motion vectors represent an activity measure of the temporally closest anchor frame.

23. (Currently Amended) The computer machine-readable ~~physical storage~~-medium of claim 22, wherein the motion vector is determined by a sum of absolute differences in activity within the temporally closest anchor frame.
24. (Currently Amended) The computer machine-readable ~~physical storage~~-medium of claim 20, wherein the plurality of anchor frames and B-frames contain progressive video content.
25. (Currently Amended) The computer machine-readable ~~physical storage~~-medium of claim 20, wherein the plurality of anchor frames and B-frames contain interlaced video content.